# Watermarking Polygonal Lines Using an Optimal Detector On the Fourier Descriptors Domain

### Introduction

\* Polygonal Line: ordered set of vertices, connected by straight traces that describe an open or a closed line. Polygonal lines are present in GIS cartographies, vector graphics or contour descriptions. \* Digital Watermarking: Information embedding in digital material, usually

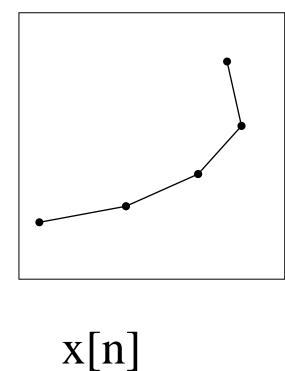
to stamp a copyright mark. **\*** Watermarking a Polygonal Line consists on slightly modifying the vertices of the line, so that the polygonal line does not suffer essential changes while carrying some extra information.

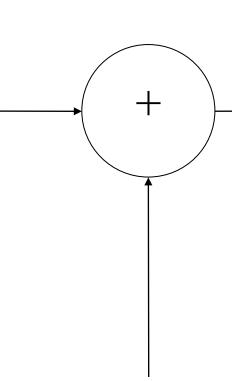
**Contour watermarking is achieved by modifying the Fourier Descriptors** magnitude in an imperceptible way.

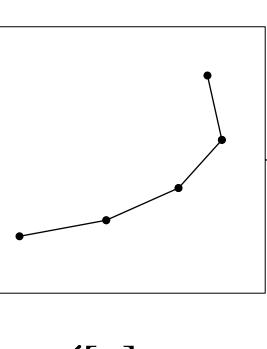
\* Robustness is a desired property of the watermark that consists on the difficulty to remove that extra information from the Polygonal Line, on despite of intentional or unintentional manipulation of the line.

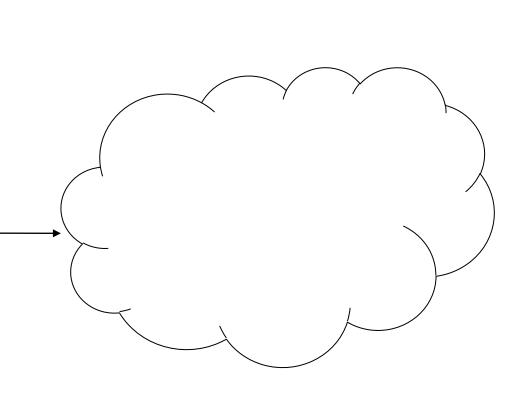
**\*** Watermarks generated by this technique can be successfully detected even after rotation, translation, scaling or reflection of the host polygonal line.

# Watermark embedding





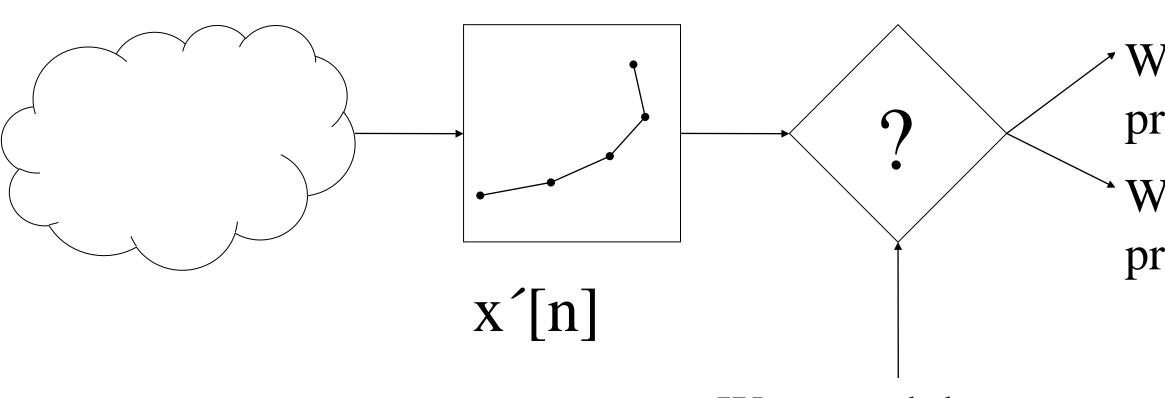




x'[n]

Watermark key

# Watermark detection



Watermark key

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# Watermark embedding

- Aimed at imperceptibly embedding a secret key in the polygonal line.

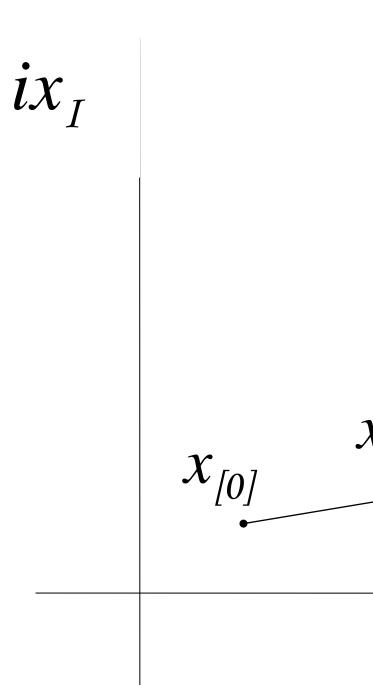


Fig. 1. Polygonal Line 2) The *Fourier Descriptors* are the coefficients of the DFT performed on x[n]:

$$\mathbf{X[k]} = \sum_{n=0}^{N-1} x[n] \exp\left(\frac{-i2kn\pi}{N}\right), 0 \le k \le N-1$$

- 3) The Watermark sequence is a binary pseudorandom sequence taking the value  $\pm 1$ . The sequence is generated from a secret key.
- 4) The watermark is embedded in the Fourier Descriptros according to the multiplicative formula:

$$|X[k]] = |X[k](1+sW[k]), k = 0, 1, ..., N-1$$

- 5) An inverse DFT is performed to obtain the coefficients x'[n] of the watermarked line
- Aimed at determining whether a secret key is present or not in a polygonal line x[n].
- \* The simplest approach is to calculate the **correlation** of the line with the watermark:

$$C = \frac{1}{N} \sum_{k=0}^{N-1} |X[k]W[k]|$$

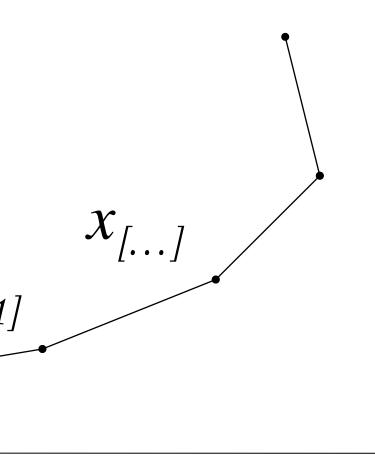
The correlation value C is compared against a threshold T.

\* The statistical detection theory states that the correlation is the optimal signal graphics, SVG etc.) (watermark) detector if the noise (host signal) is additive and the noise samples are Any polygonal line with more than 1000 points is suitable for being watermarked. independent random variables following a Gaussian distribution. These assumptions do not hold and the correlator detector can be improved.

' Watermark present Watermark NOT present

1) The *Polygonal Line* is considered as an ordered set of points in the complex space.

The Likelihood Ratio Test compares the conditional probabilities of the polygonal line **X** to belong to the hypothesis of watermark presence  $(H_1)$  or absence  $(H_0)$ :



 $\mathcal{A}_{\mathcal{R}}$ 

Watermark detection

If the samples X[k] are assumed to be independent, then:

 $\diamond$  The probability distribution function f is supposed to follow a Raileigh distribution :

\* Mean and variance are estimated from the signal X, and are assumed constant at least for small intervals of k.

\* Due to the properties of the Fourier Descriptors, a watermarked polygonal line keeps the watermark even if has suffered from several geometrical distortions.

Rotation Scaling Translation

reliability.

the European Union (www.visnet.org)

# **Optimal detection**

$$\Lambda = \frac{p(\mathbf{X}|H_1)}{p(\mathbf{X}|H_0)} \begin{cases} H_1 \\ > \\ T \\ H_0 \end{cases}$$

$$(\mathbf{X}|H_j) = \prod_{k=0}^{N-1} p(\mathbf{X}[k]|H_j), j = 0,1$$

\*It is supposed that  $p(X[k]|H_0)$  follows a known probability distribution function f. As the watermark embedded is a linear operation, the conditional probability  $p(X[k]|H_1)$  can also be expressed in terms of f. Thus, the Likelihood Ratio Test is:

$$\frac{\prod_{k=0}^{N-1} f(X[k](1+sW[k])) H_1}{\prod_{k=0}^{N-1} (1+s)f(X[k])} \gtrsim T$$

$$(X[k]) = \frac{|X[k]|}{\sigma_k^2} \exp\left(-\frac{|X[k]|^2}{2\sigma_k^2}\right)$$

# **Properties**

- Change of traversal starting vertex
- Inversoin of traversal direction
- Mirroring

# **Conclusions**

This is a watermarking system for polygonal lines (application in GIS, vector

As statistical methods are used, the higher the number of points, the better the

More work on real multiple-line images should be done.

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